CURRICULAR STRUCTURE FOR PART- III (3RD YEAR) OF THE FULL TIME DIPLOMA COURSES IN ENGINEERING AND TECHNOLOGY

WEST BENGAL STATE COUNCIL OF TECHNICAL EDUCATION TEACHING AND EXAMINATION SCHEME FOR DIPLOMA IN ENGINEERING COURSES COURSE NAME: FULL TIME Diploma in Instrumentation and Control Engineering **DURATION OF COURSE: 6 SEMESTERS** SEMESTER: SIXTH **BRANCH: ENGINEERING CREDITS** SR. **SUBJECT PERIODS EVALUATION SCHEME** NO. INTERNAL Total @TW TU PR **ESE** PR **SCHEME** Marks TA \mathbf{CT} **Total Industrial** 1. 3 10 20 Management 3 30 70 100 Advanced 2. Microprocessor 3 3 1 10 20 30 70 100 and Microcontroller **Biomedical** 3. 10 **50** 2 2 5 15 35 Instrumentation **Power Plant** 2 4. 5 10 15 35 **50** Instrumentation Elective (Any One) a)Automation **Solution** 5 10 15 35 **50** 5. b)Computer Aided 2 2 -Instrumentation c)Computer Hardware & Networking Advanced Microprocessor 6. 2 3 100 100 and Microcontroller Laboratory **Power Plant** 8. Instrumentation 1 3 50 50 Laboratory **Circuit Simulation** 9. 2 3 100 100 and Control 1 **Simulation Laboratory** Elective (Any One) a) Automation Solution Laboratory b)Computer Aided 10. 1 2 50 50 Instrumentation Laboratory c)Computer Hardware &Networking Lab 11. **General Viva Voce** 3 2 100 12. **Industrial Project** 3 3 100 **Professional** 1 50 11. Practice - IV 2 50

135

315 300

50

900

Total

25

13 1

15

45

90

STUDENT CONTACT HOURS PER WEEK:33 hrs, (Teaching-15 weeks + Internal Exam-2 weeks)

THEORY AND PRACTICAL PERIODS OF 60 MINUTES EACH.

ABBREVIATIONS: L- Lecture, TU- Tutorials, PR- Practical, TA- Teachers Assessment, CT- Class Test, ESE- End Semester Exam, @TW-Term Work

TA (Teacher's assessment) = 10 marks: Attendance & surprise quizzes = 5 marks and Assignment & group discussion = 5 marks for CT= 20Marks.

TA (Teacher's assessment) = 5 marks: Attendance & surprise quizzes + Assignment & group discussion = 5 marks for CT = 10 Marks.

Total Marks: 900

Minimum passing for Sessional marks is 40%, and for theory subject 40%.

Assessment of Practical, Oral & term work to be done as per the prevailing norms of curriculum implementation & assessment

Syllabus for INDUSTRIAL MANAGEMENT

Note: This is common for all departments.

Syllabus for ADVNCED MICROPROCESSOR & MICROCONTROLLER

Name of th	ne Course : Diploma in Instrumentation	n and Control Engineering				
Name of th	ne subject : Advanced Microprocessor &	& Microcontroller				
Subject Co	ode:	Semester: Sixth				
Duration:	6 months	Maximum Marks: 100				
Teaching S	Scheme:	Examination Scheme:				
	: 3hrs/week	Internal Scheme: Teachers Assessment: 10				
	al: 1hrs/week	Class Test : 20				
Praction	cal:	End Semester Exam : 70				
Credit: 3		1				
Aim:						
Sl No.						
1	Today microprocessors and microcontrollers have become an integral part of all automatic and semi automatic machines. Therefore there is a growing need of engineers / technicians in this field. Hence, it is necessary to study microcontroller basics, hardware and its programming.					
2	The study of Advance Microprocessor & Microcontroller is based on the essential requirements of detail knowledge of architectural design of Intel 8086 microprocessor chip & 8051 Microcontroller					
3	The technology of microprocessor has led to a single chip Microcontroller technology MCS-51 family architecture, details of 8051 Microcontroller and its programming is covered in this subject use of assembler and stimulator for programming of Microcontroller will make the students equipped for the development of embedded systems.					
Objective	<u> </u>					
Sl No.						
1	Use data transfer techniques.					
2	Describe architecture and operation of	microcontroller 8051.				
3	Develop assembly language programs	using instruction set of 8051.				
4	Design and develop microcontroller ba					
5	Explain various applications of microco	ontrollers.				
Pre-requis	site:					
Sl No.						
1	knowledge of digital electronics					
2	knowledge of 8085 microprocessor					

Group	Module	Contents Name of the topics	Hrs
Group	Module	8086 and its Architecture:	/ Modul
A	1	1.1 Intel 8086 processor, pin details for max. mode & min. mode. 1.2 8086 CPU architecture, bus interface unit & execution unit, pipelined architecture. 1.3 Register organization & different addressing mode of 8086 1.4 Basic idea of some of the advanced features- concept of multi programming, interleaved memory, cache memory, multi processing.	8
	2	Memory Organisation 8086: 2.1 Memory Addressing 2.2 Instruction set of 8086 2.3 Writing Assembly Language Programme	7
	3	Microcontroller 8051 Architecture 3.1 Difference between microcontroller & Microprocessor. 3.2 Explain the Block diagram of the Architectural of 8051. 3.3 Explain the PIN Diagram features of the 8051 core. 3.4 Explain the 8051 Programming Model. 3.5 Explain the Port Structure & Operation, Timer/Counters, serial Interface & External memory	8
	5	 8051 Addressing Modes & Instruction Set 5.1 Explain different addressing modes of 8051. 5.2 Explain the different types of Instruction sets of 8051. 5.2.1 Data Transfer 5.2.2 Arithmetic Operations 5.2.3 Logical Operations 5.2.4 Boolean Variable Manipulation 5.2.5 Program Branching 	10
В	6	8051 Assembly Language Programming Tools 6.1 Programs using Jump, Loop and Call Instructions, Time Delay Generation and Calculation. 6.2 I/O Port Programming, Bit manipulation 6.3 Arithmetic Programs a. Unsigned Addition and Subtraction b. Unsigned Multiplication and Division c. Signed number concept and Arithmetic operations d. Logic Programs 6.4 Programs using Logic and Compare Instructions a. Programs using Rotate and Swap Instructions b. BCD and ASCII Application Programs 6.5 Counter / Timer Programming 6.6 Programming 8051 Timers 6.7 Counter Programming 6.8 Serial Communication Programming a. Basics of Serial communication b. 8051 Connection to RS232 c. 8051 Serial Communication Programming 6.9 Interrupts Programming 8051 Interrupts a. Programming Timer Interrupts b. Programming External hardware Interrupt c. Programming the Serial Communication Interrupt d. Interrupt Priority in the 8051	12

	7	7.1 7.2 7.3	Speed/po		l ol of ac/dc m arameter like		sure, flow	etc		5
Books:										
Title					Author			Pub	olisher	
Micropr	ocessor 2	rchitecti	ıre, progra		R.S.Gaonka	•		Wie		
& applic		пстисси	ire, progre		r.s.Guoma			**10	.i.y	
- 11	ocessor& l	Microco	ntroller		N Senthil			Oxf	ord University	v press
	Microprocessor and Microcontroller					vanan, Jee	vananthan		ord University	
			& Application		Pal			PHI		/
			& Embeded		Mazidi, Maz	zidi		PHI	[
		/licrocon			K J Ayla				ram Internatio	nal
Architec	ture, Progr	ramming	and Applic	ation	· ·					
Introduc	tion to Mic	croproce	ssor		A.P. Mathu	r		TM	H	
	Circuits &				Herbert taub			TMH Pub.		
	er system A				Morris Mano			PHI India		
	er organiza				P.Pal Choudhuri			PHI		
Design v	vith PIC M	licrocon	troller		J B Peatman			Pearson		
	ed Systems				C.R Sharma				versity Press	
Advance	d Micropr	ocessor o	& Microcon	troller	Prof. S K Venkata Ram				versity Science	
								(Laxmi Publications Pvt. Ltd)		
8086 pro		g & adva	nced proces		Savaliya			Wil	ey India	
Advance	ed micropr	ocessor (& periphera	1	A k Ray & K M Burchandi			TMH		
Advance	ed Micropi	rocessor			B Ram			ТМН		
				End Seme	ster Examin	ation Sche	me			
		Max	kimum Marl	ks: 70			Т	ime:	3 Hrs	
			Object	ive Questio	ns		Subjec	tive (Questions	
Group	Module	To be	To be	Marks per	Total	To be	To be		Marks per	Total
		set	answered	question	Marks	set	answered	1	question	Marks
	1									
A	2	12				4	Any 5			
	3	- -			1 x 20		taking a			10 x 5
	4		Any 20	1	=20		least 2	. [10	=50
-	5	10					from eac	h		
В	6	13				4	group			
	7					1				

$Syllabus \ for \ BIOMEDICAL\ INSTRUMENTATION$

Name of the Course : Diploma in Instrumentation and Control Engineering					
Name of the Subject : Biomedical Instrumentation					
Subject Code:	Semester: Sixth				
Duration: 6 months	Maximum Marks: 50				

7D 13	. 0.1								
	ing Scheme ry: 2hrs/								
Tutor		Class Test : 10							
Pract		End Semester Exam : 35							
Tract	icai .	End Schlester Exam							
Credit: 2									
Aim:									
Sl No.									
1		y of Biomedical Instrumentation is a vital subject for the students at the present age, omedical Electronic Instruments used for getting biological information of the huma							
		for investigation.	n being						
Objectiv									
Sl No.		The Student will able to							
1		e application of the biosensors and detectors							
2	Know ap	plication of different biomedical Instrument							
Pre-requ	l iisite:								
Sl No.									
1	Fundame	ental idea of Instrumentation system							
2	Basics of	electronics							
3	Basics of								
	I	Contents	TT						
Group	Module	Name of the topics	Hrs / Module						
	1	Physiological System and Bio-signals	5						
		1.1 Physiological system of the body1.2 Function structure of the cell							
		1.2 Function structure of the cell 1.3 Resting and Action potentials							
		1.4 Function of heart							
		1.5 Physiological signal amplifier							
	2	Electrodes, sensors &Transducers for Biomedical Application	7						
		2.1 Electrodes for biophysical sensing							
A		2.2 Resistive transducers – Muscle force and Stress (Strain guage, Spirometry	,						
		(Potentiont), humidity, (Gamestrers), Respiration (Thermistor)							
		2.3 Inductive Transducers – Flow measurements, muscle movement (LVDT)							
		2.4 Capacitive Transducers – Heart sound measurement, Pulse pick up							
		2.5 Photoelectric Transducers – Pulse transducers, Blood pressure, oxygen Analyses							
		2.6 Piezoelectric Transducers – Pulse pickup, ultrasonic blood flowmeter							
		2.7 Chemical Transducer – Ag-Agfallas (Electrodes, pH electrode)							
	3	Measurement of Biological & Physiological parameter	8						
		3.1 Measurement of blood pressure, blood volume, respiration rate,							
		temperature, ECG, EEG, EMG, PCG 3.2 Safety measures implemented in Biomedical Instrumentation							
	4	Patient Monitoring System and ICU assisting device	7						
		4.1 Intensive cardiac care unit and central monitoring system							
В		4.2 Patient monitoring through biotelemetry							
ט		4.3 Pacemaker 4.4 Defibrillators							
		4.5 Ventilators & Respirators							
		1.0 - Chilitatoro & Respiratoro							
	5	Medical Imaging System	3						
	5	Medical Imaging System 5.1 X Ray machine	3						
	5	5.1 X Ray machine	3						
	5		3						

chor bster r, Brown mwell, Weibell, Pfeiffer . khandpur ng, Tsui, Smith I Pandey	Publisher Wiley India Pearson Education PHI TMH Academic Press Inc S. K. Khataria
mwell, Weibell, Pfeiffer . khandpur .ng, Tsui, Smith	PHI TMH Academic Press Inc
. khandpur ing, Tsui, Smith	TMH Academic Press Inc
ing, Tsui, Smith	Academic Press Inc
I Pandev	S K Khataria
· I dilacj	S. II. IIIIuuuiu
ldes & Baker	Wiley
jay Guha	University Publication
jay Guha	University Publication
S Sawhney	Dhanpat Rai & Co.
Ananda Natarajan	PHI
Raja Rao	University Press
F	Ananda Natarajan Raja Rao

End Semester Examination Scheme

		Ma	ximum Mar	ks: 35	Time: 2 Hrs					
			Objecti	ive Question	S	Subjective Questions				
Group	Module	To be	To be	Marks per	Total	To be	To be	Marks per	Total	
		set	answered	question	Marks	set	answered	question	Marks	
A	1	6				2	Any 5			
	2	7	l			1 x 10	3	taking at		5 x 5
В	3		7 Any 13	1	=10		least 2	5	=25	
	4				10	5	from each			
	5						group			

Syllabus for POWER PLANT INSTRUMENTATION

the Course: Diploma in Instrumenta	tion and Control Engineering					
the Subject: Power Plant Instrument	ation					
Code:	Semester: Sixth					
Duration: 6 months Maximum Marks: 50						
Scheme:	Examination Scheme:					
ory: 2hrs/week	Internal Scheme: Teachers Assessment: 05					
rial:	Class Test : 10					
tical :	End Semester Exam : 35					
2						
	t in different industries as well as power generation unit.					
	the Subject : Power Plant Instrument Code: :: 6 months g Scheme: ory : 2hrs/week rial : cical :					

Objectiv	ve:								
Sl No.		ent will able to							
1	Measure o	lifferent parameter like tempera	ture, level, flow, vibration etc.						
2			/ fuel ratio, superheated steam te	mperature, turbine v	ibration et				
Pre-requ	iisite:								
Sl No.	T.1	-1							
<u>1</u> 2		asic control logic and terminologusic electronics	<u> </u>						
	idea on ba	isic electronics							
			Contents						
Group	Module		Name of the topic		Hrs/ Module				
	1	Overview of Power Generati	on		5				
		Brief survey of method:	s of power generation-hydro, the	rmal, nuclear,					
		solar and wind power							
	Importance of Instrumentation in power generation								
	Thermal power plant –building blocks, details of boiler								
	2	Measurement			3				
		Measurement of temperature, pressure, flow vibration etc (in brief.)							
A		,, p, (61.61.)							
	3	Control Loops in Boiler							
		Combustion Control							
		Air/Fuel ratio							
		Control Furnace							
		draft control Drum							
		level control							
			steam temperature control						
		Superheater control							
		Deaerator control							
		DCS in power plant							
		Interlocking in boilers							
	4	Turbine - Monitoring & Control							
		Speed, vibration, shell temperature monitoring & control							
		Steam pressure control							
		Lubricant oil temperat	cure control						
		Cooling system							
В	5	Data handling-processing							
	3	logging, acquisition, accounting, display and storage							
		Instrumentation for Generator and Busbar coupling Introduction to							
		power plant modeling.							
Books:									
Title			Author	Publisher					
		rial Instrumentation,	D. Patranabis,	TMH					
		rs Handbook Vol & II	Liptak,	Butterworth	1				
	ant Instrum		Krisnaswami, M P Bala	PHI					
Power Pl	ant Control	& Instrumentation	David Lindsley	Institute of	Electrical				
F1 ~	. 1 0= ::			Engineers					
	trol of Boile		S G Dukelow	ISA					
		on Practice-Instrumentation,			ress,				
Controls			į.	1 ()vtord	Pergamon Press, Oxford				

Oxford

Controls

Standard	Boiler Op	peration			S. M. Elonka, A. L. Kohal			TMH	
Boiler Co	ontrol Sys	tems Engi	ineering		G.F. Gilman			ISA Publication.	
Power Pl	ant Engin	eering			P.K.Nag			. McGraw	Hill.
Power Pl	ant Instru	mentation	& Control		Philip Kia	ameh			
	End Semester Examination								
		N	Maximum Ma	rks: 35			Time: 2 Hrs		
Group	Module	Objective Questions				Subjective Questions			
		To be set	To be answered	Marks per question	Total Marks	To be set	To be answered	Marks per question	Total Marks
A	1 2 3	7	Any 10	1	1 x 10 =	4	Any 5 taking at least 2 from each	5	5 x 5 = 25
В	5	6			10		group		

Syllabus for AUTOMATION SOLUTION

Name of the Cou	rse: Diploma in Instrumentation and	Control Engineering				
Name of the Sub	ect : Automation Solution					
Course Code:		Semester: Sixth				
Duration: 6 mon	hs	Maximum Marks: 50				
Teaching Scher Theory : 2 Tutorial : Practical :	ne: nrs/week	Examination Scheme: Internal Scheme: Teachers Assessment: 05 Class Test : 10 End Semester Exam : 35				
Credit: 2						
Aim:						
Sl No.						
1	This subject will develop a student t	o make worthy for any industry				
Objective:						
Sl No.	The Student will able to					
1	Program PLC					
2	Know about the function of DCS					
3	Operate CNC	acasta c				
4	Know about the Robots and its prog	тапши				
Pre-requisite:						
Sl No.						
1	Idea on basic control system					
2	Idea on basic electronics					
		Contents				
Group Modu	lle N	ame of the topic Hrs/ Module				

	1	Overview of Automation Idea on PID Idea on a close loop system with real example of different instrument needed	1
A	2	 Programmable Logic Controller Introduction to PLCs, Areas of applications Architecture of a typical PLC, operation of PLC Difference between PLC and Hardware system, Relay logic and Ladder Logic Programming of PLCs, systematic solution finding Programming languages, PLC Programmers, PC interface Function block diagram, ladder diagram, instruction list, structured text Sequential function chart, logic control systems, timers, counters Commissioning and operational safety of a PLC, data transmission interface and communication in the field area Guidelines and standards 	8
	3	 Distributed Control System: Features of DCS PLC and DCS – a comparative study Architecture of a Typical DCS system Advantage & Disadvantage of DCS Hardware arrangement of DCS for a complete close loop system for analog as well as digital control Concept of graphic panel, control panel, tuning panel, alarm panel etc 	7
	4	 Concept of Robotics: Definition of Robot and Robotics, functional components of Robot Different types of robot joints, workplace, work volume, work envelop, degree of freedom of robot Common types of configuration used in major linkage or arm Description of Cartesian coordinate robot Robot Sensors: internal (joint position, speed sensor, acceleration, force, torque), external tactile, proximity, long range) Robot application- loading unloading, material handling etc 	7

	5	Concept of Computer Numerical Control:	7
		 Introduction to NC, CNC, DNC, Advantages and disadvantages of CNC 	
		over conventional machine tool	
		 Block Diagram of a CNC system, Physical components of CNC (MCU, Monitor, Machine TOOL) 	
_		Type of CNC machine (CNC lathe, CNC milling , Machining Centre)	
В		CNC machine Classification	
		 Feed back system (open loop / close loop_) 	
		Control system (Point to point , Straight cut, contour system)	
		• CNC machine co ordinate system ,x,y,z axis directions-absolute co ordinate	
		system, Incremental co ordinate system)	
		Part programming (Manual & computer aided)	
		Manual part programming	
		Word & Block	
		Various functions (Words) (N word, Gword, X,Y,Z word, F word,	
		S word, M words)used in manual part programming	
		simple program in CNC lathe for facing, straight turning, taper turning, circular inter polation	
		Coordinate system setting—Strarting point, Fixed zero, floating	
		Zero	
		Steps involved in CNC operation	

В	0	0	k	S	:

Title	Author	Publisher
Programmable Logic Controllers	Thomas E. Kissel	
Programmable Logic Controllers	Weib & Reis	PHI
Instrument Engineers Handbook Vol & II	Liptak,	Butterworth
Process control Instrumentation Technology	Johnson	Prentice Hall of India
Programmable Logic Controller	Job Dan Otter	P.H. International Inc, USA
Process Control Principle and Application	Bhanot	Oxford university press
Robot Dynamics & Control	Spong, Vidyasagar	Wiley
Computer Numerical Control Machine	P Radhakrisnan	New Central Book Agency
Computer Numerical Control- Operation &	Stenerson & Curren	PHI
Robotics Engineering	Klafter, Chmielewski, Negin	PHI
Industrial Robotics	Groover, Wises, Nagel, Odrey	Mcgraw Hill
Industrial Robotics	B. Hodges	JAYCO
Robotic Technology and Flexible Automation	S. Rajan	TMH
CNC Programming Made Easy	B K Jha	Vikas
Robotics: Introduction, Programming and Projects	Maxwell	Macmillan
Programmable Logic Controller	T. E. Kissel	
Programmable Logic Controller	J. D Otter	P. H. International

End Semester Examination

		N	Iaximum Maı	Time: 2 Hrs					
		Objective Questions					Subjective	Questions	
Group	Module	To be	To be answered	Marks per question	Total Marks	To be set	To be answered	Marks per question	Total Marks
A	1 2	7	Any 10	1	1 x 10 =	4	Any 5 taking at least 2	5	5 x 5 = 25
В	3 4	6	7 my 10	1	10	4	from each group	3	3 K 3 = 23

${\bf Syllabus\ for\ COMPUTER\ AIDED\ INSTRUMENTATION}$

Name of	f the Cours	e : Diploma in Instrumentation and C	Control Engineering	
		t: Computer Aided Instrumentation		
Subject		•	Semester: Sixth	
Duration	n: 6 months	}	Maximum Marks: 50	
Scho Theo Tuto Prac	ching eme: ory : 2hrs orial : tical :	/week	Examination Scheme: Internal Scheme: Teachers Assessme Class Test End Semester Exam	ent: 05 : 10 : 35
Credit: 2	2			
Aim: Sl No.				
2	detail know	•	ntation is based on the essential requirer ter & interfacing to field system using dif- computer for industrial application	
Objectiv	ve:			
Sl No.		tudent will able to		
1		Bus standard, virtual instrumentation e	tc	
2	Use s	erial, parallel, USB port		
Sl No.				
2		Electronic Engineering ation of Computer		
	Opera	ation of Computer		
	, ,	C	ontents	1
Group	Module		ne of the topic	Hrs/ Module
	1	Comparison with other control	of computer based instrumentation	2
	2	Buses & Standards: Introduction, Bus type, The I/O RS-232 USB) bus ISA bus, EISA bus, PCI bus, GPIB,	2
A	3	Virtual Instrumentation: • Basics concepts of virtual instrumentation	rumentation, Need.	2
	4	Computers in Process Control:	a logging , Supervisory control, Computer	3

5	Linear Circuit and Signal Conditioning: Op-amps, Instrumentation amplifiers and signal conditioning, Multiplexer and demultiplexer, ADC and DAC.	3
6	Parallel Port (PP) Interfacing Technique Introduction to parallel port , Parallel port as output port , Programming of Parallel port as input / output port.	4
7	Serial Port (SP) Interfacing Technique: Introduction to serial port, Serial port as output port, Programming of Serial port as input / output port.	4
8	USB Port Interfacing Technique: Introduction to USB port, USB port as output port	4
9	Use of Instrumentation Package: Like Lab VIEW / DAISY LAB / GENIE GRAPHICAL PROGRAMMING	3
10	Case Study: CNC motion controller ,Power plant controller ,Cement plant control Sugar plant control, Textile plant control	3
	6 7 8	Op-amps, Instrumentation amplifiers and signal conditioning, Multiplexer and demultiplexer, ADC and DAC. Parallel Port (PP) Interfacing Technique Introduction to parallel port, Parallel port as output port, Programming of Parallel port as input / output port. Serial Port (SP) Interfacing Technique: Introduction to serial port, Serial port as output port, Programming of Serial port as input / output port. USB Port Interfacing Technique: Introduction to USB port, USB port as output port Use of Instrumentation Package: Like Lab VIEW / DAISY LAB / GENIE GRAPHICAL PROGRAMMING Case Study: CNC motion controller, Power plant controller, Cement plant control Sugar

Books:

Title	Author	Publisher
PC Based Instrumentation: Concept &	Mathivanan	PHI
Practice		
PC Based Instrumentation & Control	Mike Tooley	Elseveir Butterworth Heinemann
PC Interfacing for Data Acquisition & Process Control	S Gupta	ISA

End Semester Examination Scheme

		1	Maximum N	1arks: 35	Time: 2 Hrs				
Group			Object	ive Question	S	Subjective Questions			
	Module	To be	To be	Marks per	Total	To be	To be	Marks per	Total
		set	answered	question	Marks	set	answered	question	Marks
	1								
A	2								
A	3	6				4	A 5		
	4						Any 5		
	5		A my 10	1	1 x 10		taking at least 2	5	5 x 5
	6		Any 10	1	=10		from each	3	=25
	7								
В	8	7				4	group		
	9								
	10								

Syllabus for COMPUTER HARDWARE & NETWORKING

Name of	the Course	: Diploma in Instrumentation and Control Engineering							
		: Computer Hardware & Networking							
Subject C	Code:	Semester: Sixth							
Duration:	6 months	Maximum Marks: 50							
Teaching	Scheme:	Examination Scheme:							
	y : 2hrs/v		t: 05						
Tutor		Class Test	: 10						
	Practical: End Semester Exam : 35								
Credit: 2									
Aim:									
Sl No.									
1		y of Computer Hardware & Networking is based on the essential requirements ge of architectural design of computer hardware & networking using different software							
2	To Identi	fy various components of PC							
3		construction, working and function of different peripheral devices.							
4	To Instal	system software, application software, drivers and detect /remove virus infections							
Objective									
Sl No.		ent will able to							
1		various components of PC.							
2		the construction, working and function of different peripheral devices.							
3		interpret documentation (use manuals).							
4		e the PC and connect the modules.							
5		stem software, application software and drivers.							
6		e components for proper function, correct faults.							
7		d handle the diagnostic and test software.							
8		d remove virus infections.							
9	_	ferent types of networks and components used in networking							
	State dir	to the types of new orac and components along in new orang							
Pre-requ	isite:								
Sl No.									
1		lectronics Engineering							
2	Operation	n of Computer							
		Contents							
Group	Module		Hrs						
•		Name of the topic	/ Module						
	1	Personal Computer	2						
		1.1 Evolution – IBM PC to Pentium, Laptops, Palmtops.							
	1.2 Personal computer system – functional block diagram, recognize								
		major components of PC							
		1.3 Technical specifications.							
		1.4 Comparison chart – processor and memory IBM PC to Pentium IV, AMD							
		athlon, Sempron etc.							
		1.5 System unit – brief description of motherboard, interface cards,							
ı		expansion slots, front panel control, rear side connectors, cables and							
ı		connectors, SMPS, floppy disc drive, hard disc drive, CD-ROM drive, display unit, keyboard.							
		unve, uispiay unit, keyuuatu.							

	2	Inside PC	6
	_	2.1 Inside PC – functional blocks of mother board – CPU, RAM, BIOS,	O
		CacheRAM, BUS extension slots, on-board I/O and IDE connectors,	
		ISA, PCI, AGP & PCI express.	
		2.2 BIOS, services, organization and interaction.	
		2.3 CMOS, CMOS setup utilities, CMOS setup program.	
		2.4 Motherboard types.	
		2.5 Processors – CISC and RISC.	
		2.6 Features of Pentium 4 processor, Pentium Celeron processor, CYRIX	
A		series processors, AMD series processors.	
		2.7 Chipsets – features of Intel 800, 810, 854, 915 series chipset motherboards	
		2.8 Bus standard and Bus architecture	
		2.9 Power supplies – Linear power supplies, SMPS, block diagram of	
		SMPS, Linear vs SMPS power supply, SMPS for computers, Power	
		requirements in PCs.	
	3	On board memory and I/O interface	3
		3.1 PC's memory organization	
		3.2 ROM, RAM, distinguish between static and dynamic RAM	
		3.3 DRAM, Synchronous DRAM, Extended Data Out DRAM, Double Data	
		Rate SDRAM, Direct Rambus DRAM, Cache	
		Memory, Extended/Expanded/Virtual memory.	
		3.4 PC memory map, Memory packaging.	
		3.5 I/O port – Serial port, Parallel port, Game port, USB port	
	4		4
	4	Storage devices	4
		4.1 Magnetic storage fundamentals – read/write head, writing, reading.	
		4.2 Diskette basics – Floppy disks, Hard disks, tracks and sectors, disk types.	
		4.3 Disk organization in DOS	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy 	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing 	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions 	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions 	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions 	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions and functional block diagram, interfacing of HDC, SATA technology. 	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions and functional block diagram, interfacing of HDC, SATA technology. 4.6 Installation and configuration of HHD – configuring, 	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions and functional block diagram, interfacing of HDC, SATA technology. 4.6 Installation and configuration of HHD – configuring, formatting, partitioning. 4.7 CD-ROM disks – types, reading and writing of CD 	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions and functional block diagram, interfacing of HDC, SATA technology. 4.6 Installation and configuration of HHD – configuring, formatting, partitioning. 4.7 CD-ROM disks – types, reading and writing of CD 4.8 CD-ROM drive – principle of operation, block diagram, installation 	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions and functional block diagram, interfacing of HDC, SATA technology. 4.6 Installation and configuration of HHD – configuring, formatting, partitioning. 4.7 CD-ROM disks – types, reading and writing of CD 4.8 CD-ROM drive – principle of operation, block diagram, installation and setup. 	
		 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions and functional block diagram, interfacing of HDC, SATA technology. 4.6 Installation and configuration of HHD – configuring, formatting, partitioning. 4.7 CD-ROM disks – types, reading and writing of CD 4.8 CD-ROM drive – principle of operation, block diagram, installation and setup. 4.9 DVD technology – DVD disks, DVD drive, block diagram, DVD formats. 	
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	5	 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions and functional block diagram, interfacing of HDC, SATA technology. 4.6 Installation and configuration of HHD – configuring, formatting, partitioning. 4.7 CD-ROM disks – types, reading and writing of CD 4.8 CD-ROM drive – principle of operation, block diagram, installation and setup. 4.9 DVD technology – DVD disks, DVD drive, block diagram, DVD formats. 4.10 Pen drives. 4.11 Installing CD and DVD media drives. Input Devices 5.1 Keyboard – types, operation, and keyboard signals, interface 	2
	5	 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions and functional block diagram, interfacing of HDC, SATA technology. 4.6 Installation and configuration of HHD – configuring, formatting, partitioning. 4.7 CD-ROM disks – types, reading and writing of CD 4.8 CD-ROM drive – principle of operation, block diagram, installation and setup. 4.9 DVD technology – DVD disks, DVD drive, block diagram, DVD formats. 4.10 Pen drives. 4.11 Installing CD and DVD media drives. 	2
	5	 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions and functional block diagram, interfacing of HDC, SATA technology. 4.6 Installation and configuration of HHD – configuring, formatting, partitioning. 4.7 CD-ROM disks – types, reading and writing of CD 4.8 CD-ROM drive – principle of operation, block diagram, installation and setup. 4.9 DVD technology – DVD disks, DVD drive, block diagram, DVD formats. 4.10 Pen drives. 4.11 Installing CD and DVD media drives. Input Devices 5.1 Keyboard – types, operation, and keyboard signals, interface 	2
	5	 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions and functional block diagram, interfacing of HDC, SATA technology. 4.6 Installation and configuration of HHD – configuring, formatting, partitioning. 4.7 CD-ROM disks – types, reading and writing of CD 4.8 CD-ROM drive – principle of operation, block diagram, installation and setup. 4.9 DVD technology – DVD disks, DVD drive, block diagram, DVD formats. 4.10 Pen drives. 4.11 Installing CD and DVD media drives. Input Devices 5.1 Keyboard – types, operation, and keyboard signals, interface logic, keyboard functions. 	2
	5	 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions and functional block diagram, interfacing of HDC, SATA technology. 4.6 Installation and configuration of HHD – configuring, formatting, partitioning. 4.7 CD-ROM disks – types, reading and writing of CD 4.8 CD-ROM drive – principle of operation, block diagram, installation and setup. 4.9 DVD technology – DVD disks, DVD drive, block diagram, DVD formats. 4.10 Pen drives. 4.11 Installing CD and DVD media drives. Input Devices 5.1 Keyboard – types, operation, and keyboard signals, interface logic, keyboard functions. 5.2 Mouse – principle of operation, mouse signals, optical mouse, mouse installation. 	2
	5	 4.3 Disk organization in DOS 4.4 Floppy disk drives – types and capacity, drive sub assemblies, floppy disk controller – functions and functional block diagram, interfacing of FDC 4.5 Hard disk drives – drive sub assemblies, hard disk controller – functions and functional block diagram, interfacing of HDC, SATA technology. 4.6 Installation and configuration of HHD – configuring, formatting, partitioning. 4.7 CD-ROM disks – types, reading and writing of CD 4.8 CD-ROM drive – principle of operation, block diagram, installation and setup. 4.9 DVD technology – DVD disks, DVD drive, block diagram, DVD formats. 4.10 Pen drives. 4.11 Installing CD and DVD media drives. Input Devices 5.1 Keyboard – types, operation, and keyboard signals, interface logic, keyboard functions. 5.2 Mouse – principle of operation, mouse signals, optical mouse, mouse installation. 	2

	6	Vide	o and Soun	d					2		
		6.1	Display								
		6.2		sics – CRT,	scanning m	ethods co	olour CRT				
			 6.3 VGA monitor – Functional block diagram 6.4 Digital display technology (thin displays) – Liquid crystal displays, LCD 								
		0.4		splay, Plasma				piays, LCD			
		G E				1 1 IIIOIII	1018.				
6.5 CRT controller - functions											
	6.6 Graphic card – Accelerated Video Cards, components of graphic cards, 3										
			video.	C 11 1 1							
		6.7					, installation and se				
				Instrument L	Device Interi	ace MID	I, 3D Audio, MPEO	j			
			audio								
	7		puter Insta						3		
		7.1					om pollution, air co	onditioning,			
				oring and cei							
		7.2					ansients, spikes and				
			_	-	wer condition	oning, sur	ge protector, voltag	ge			
			regulator								
В		1					rvo stabilizer, CVT	-			
ם							batteries, Inverters				
		7.3		•	-	_	ng motherboard, ide				
		1					modules, bios-CM				
			setup, H	D formatting	and partitic	oning, inst	tallation of system	and			
	8	Intro		networking					3		
		8.1					ea Network (WAN)				
		8.2	Network	components	s – File serve	er, workst	tations, network				
			interface	cards, netwo	ork cabling,	bridge, ro	outer, gateways,				
			repeater	(brief							
			descripti	on only)							
		8.3	Wireless	networks, n	etwork secu	rity					
		8.4	MODEM	1 – principle	of operation	n, function	nal block diagram,	installation.			
	9	Print	ters and Plo	otters					2		
		9.1	Dot matr	rix printer – į	orinciple of	operation	, sub assemblies, pr	rinter			
							tion, testing the				
			printer, c	connecting th	e printer to	the comp	uter, ribbon refillin	g.			
		9.2	LASER	printer – prir	nciple of ope	eration, fu	nctional block diag	gram,			
			toner car	tridges, prin	ter installati	on, self te	est.				
		9.3	Ink-jet p	rinter- princi	ple of opera	tion, insta	allation, installing				
			ink cartr	idges, printer	operation of	check.	_				
		9.4	Plotter –	types, functi	ional block	diagram, d	connection and				
			installati	on, inkjet plo	otters.						
		9.5	Setting o	f configurati	on switches						
Books:											
Fitle				Author		1	Publisher				
	er Installat	ion and S	Servicing	D Bala Sub	ramanian		TMH, New Delhi				
	ng and trou				ers, scott Jer		TMH, New Delhi TMH, New Delhi				
	er Fundam		5 1 03	Dr.Lariy Lo			Dreamtech Press				
	ete guide		utor	Sudipto Da			University Science	Drace			
Fundame		to Comp	utei	Sudipto Da	.8	'	Oniversity Science	F1688			
				Torontoro		1	PHI / Pearson				
	er Networl			Tanenbum	• 1•			D.			
Compu	ter Netwo	ork		Bhusan Ti	rivedi		Oxford University	y Press			
				End S	emester Ex	aminatio	on Scheme				
		M	aximum Ma		CHICAGO EA		Time: 2) Urc			
		171			20						
(oup Objective Questions Subjective										
Group	Mad-1	T - 1									
Group	Module	To be set				To be		Marks per question	Total Marks		

A	1 2 3 4 5	7	Any 10	1	1 x 10 =10	4	Any 5 taking at least 2 from each	5	5 x 5 =25
В	6 7 8 9	6			_10	4	group		-25

Syllabus for ADVANCED MICROPROCESSOR & MICROCONTROLLER LAB

Name of the Course : Diploma in Instrumentation and Control Engineering			
Name of the subject :Advanced Microprocessor & Microcontroller Lab			
Subject Code:		Semester: Sixth	
Duration: 6 months M		Maximum Marks: 100	
Teaching	Scheme:	Examination Scheme:	
Theor	y :	Continuous Internal Assessment	
Tutori		Performance of job : 30	
Practi	cal: 3 hrs/week	Notebook / viva : 20	
		External Assessment	
		On spot Job : 30	
		Viva Voce : 20	
Credit: 2			
Skill to be	e developed:		
Intellectu	ıal Skill;		
1	Use of programming language constructs in program implementation.		
2	To be able to apply different logics to solve given problem.		
3	To be able to write program		
4	Study different types of errors as syntax semantic, fatal, linker & logical		
5	Debugging of programs		
6	Understanding different steps to develop program such as		
	Problem definition		
	 Analysis 		
	Design of logic		
	• Coding		
	• Testing		
	Maintenance (Modifications, error corrections, making changes etc.)		
Motor Sk			
1	Proper handling of Computer System.		
List of Practical: Sl No. Experime			
1	Experime Study of Architecture of 8086 microprocessor		
1	Programming Language- Assembly/C		
	Programming KIT—ATMEL /		
	PIC Simple programming on (using		
2	Demonstration and study of microcontroller trainer kit		
L	√ · · · · · · · · · · · · · · · · · · ·		

3	Demonstration and use of software simulator / assembler	
4	Programming examples (any two) – Data transfer instructions	
5	Programming examples (any two) – Logical Operations	
6	Programming examples (any two) – Jump and Call instructions	
7	Demonstration and testing of the following applications (Any four)	
	Keyboard Interface	
	LCD display Interface	
	D/A or A/D converter Interface	
	Relay Interface	
	Stepper motor	
	control DC motor	
	control	

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$Syllabus \ for \ POWER \ PLANT \ INSTRUMENTATION \ LAB$

Name of the Course : Diploma in Instrumentation and Control Engineering			
Name of the subject: Power Plant Instrumentation Lab			
Subject Code:		Semester: Sixth	
Duration: 6 months		Maximum Marks: 50	
Teaching Scheme:		Examination Scheme:	
Theory: Tutorial:		Continuous Internal Assessment	
Practi	cal: 3 hrs/week	Performance of job: 15	
		Notebook / viva : 10	
		External Assessment	
		On spot Job : 15	
		Viva Voce : 10	
Credit: 1	Credit: 1		
Skill to b	e developed:		
Intellectual Skill;			
1	Operation of different instruments		
Motor Sl	Motor Skill:		
1	Proper wiring		
List of P	List of Practical:		
Sl No.	Experimen	nt	
1	Measurement of temperature by thermocouple, RTD		
2	Measurement of level by D/P transmitter		
3	Measurement of flow by orifice & D/P transmitter		
4	Measurement of pressure by pressure transmitter		
5	Control of above parameter for suitable process		
6	Simulation of any power plant		
7	Visit to any power plant		

Name	Name of the Course : Diploma in Instrumentation and Control Engineering		
	Name of the subject: Automation Solution Lab		
		Semester: Sixth	
· ·		Maximum Marks: 50	
		Examination Scheme:	
	ing Scheme: neory :	Continuous Internal Assessment	
Tutorial: Performance of job: 15 Practical: 2 hrs/week Performance of job: 15 Notebook / viva : 10		Notebook / viva : 10	
11	actical. 2 ms/week	External Assessment	
		On spot Job : 15	
		Viva Voce : 10	
~		110	
Credit			
	o be developed:		
	tellectual Skill;		
1	Understanding different steps to develop program such as		
	 Problem definition 		
	 Analysis 		
	Design of logic		
	• Coding		
	• Testing		
	Maintenance		
Moto	Motor Skill:		
1	Proper handling of Computer System.		
	List of Practical:		
Sl No.	A		
1	Learning functions of different modules of a PLC system		
2	Practical steps in programming a PLC (a) using a Hand held programmer (b) using computer interface		
3	Introduction to programming language, ladder diagram concepts, Statement List, FBD		
4	Basic logic operations, AND, OR, NOT functions		
5	Logic control operations using latching properties e.g. in activating a solenoid		
6	Sequence control system e.g. in lifting a device for packaging and counting		
7	Use of PLC for various mechanical outputs viz motion of a piston in single cylinder, multiple cylinders,		
8	driving machine operation, automatic bottle filling system, level & temperature control etc.		
9	Learning functions of different parts of a DCS system Design of different panels in DCS		
10	Programming for a close loop control system in 1	DCS	
11	Pick & place operation of Robot		
12		ht turning taper turning circular interpolation	
12	Simple program in CNC lathe for facing, straight turning, taper turning, circular interpolation.		

Syllabus for COMPUTER AIDED INSTRUMENTATION LAB

Name of the Course : Diploma in Instrumentation and Control Engineering			
Name of the subject : Computer Aided	Name of the subject: Computer Aided Instrumentation Lab		
Subject Code: Semester: Sixth			
Duration: 6 months	Maximum Marks: 50		
Teaching Scheme:	Examination Scheme:		
Theory:	Continuous Internal Assessment		
Tutorial:	Performance of job: 15		
Practical: 2 hrs/week	Notebook / viva : 10		
	External Assessment		
	On spot Job : 15		
	Viva Voce : 10		
Credit: 1			
Skill to be developed:			

Intelle	Intellectual Skill;		
1	Use of computer		
Motor	Motor Skill:		
1	Interfacing external circuitry to the computer		
List of	Practical:		
Sl No.	Experiment		
1	Controlling of relay and devices using parallel port		
2	Analog to digital conversion using ADC 0804		
3	Digital to analog conversion using DAC 0808		
4	Generation of a square wave through parallel port		
5	Implementation a data acquisition application using an 8-bit data acquisition card.		
	(Any type of software and any type of programming language like C, Visual Basic might be used)		

Syllabus for COMPUTER HARDWARE & NETWORKING LAB

Name of	the Course: Diploma in Instrumentation and Control Er	ngineering
Name of	the subject :Computer Hardware & Networking Lab	
Subject Code:		Semester: Sixth
Duration	6 months	Maximum Marks: 50
Teaching Scheme:		Examination Scheme:
Theory:		Continuous Internal Assessment
Tutor	ial:	Performance of job: 15
Practi	cal: 2 hrs/week	Notebook / viva : 10
		External Assessment
		On spot Job : 15
		Viva Voce : 10
Credit: 1		
Skill to b	e developed:	
Intellectu	ıal Skill;	
1	Identify various components of Computer.	
2	Able to prepare a block diagram to correlate all the components based on their functions.	
3	Know the procedure for starting and checking the computer function for satisfactory working.	
Motor Sl	 kill:	
1	Able to use the various tools efficiently.	
2	Identify proper tools for repair work.	
3	Start and operate the computer as per procedure.	
List of P	ractical:	
Sl No.	Experimen	
1	Open the top cover of PC unit and identify the following p	
	expansion slots, cables and connectors, rear side connections, SMPS, floppy disk and hard	
	disk drive, CD-ROM drive, RAM. Write the function of each component in brief.	

2	Find an advertisement for a new personal computer in a current newspaper or magazine and	
	examine it to determine the following –	
	Make, model and speed of CPU	
	RAM size	
	Storage capacity of HDD	
	 Does it include a CD-ROM, CD-R/W or DVD? 	
	 Does it come with network interface card? 	
	• Is a monitor included? If so, what kind and size.	
3	Assemble the PC and connect the modules. Compare layout and wiring of the module with	
	technical documents, carryout CMOS setup, organize HDD (formatting and partitioning) install	
	system software, necessary drivers, application software's and put the PC into operation.	
4	Install graphic and sound blaster card and necessary drivers.	
5	Install and handle the diagnostic test software, detect faulty components, asses the possibility of repair, repair or replace them.	
6	Detect and remove virus infection.	
7	Carryout systematic fault finding, check cables, plugs, connectors, power supply and other units.	
	Select suitable spare parts and replace the defective parts and components.	
8	Install printer, plotter and required drivers	
9	Carryout preventive maintenance and cleaning of printer. Carryout self test and adjust the printer.	
10	Install MODEM and required driver.	

Syllabus for CIRCUIT SIMULATION & CONTROL SIMULATION LAB

Name of the Course : Diploma in Instrumentation and Control Engineering		
Name of the subject : Circuit Simulation & Control Simulation Lab		
Subject Code:	Semester: Sixth	
Duration: 6 months Maximum Marks: 100		

Teaching Scheme: Examination Scheme: Theory: 1 hrs/week Continuous Internal Assessment Tutorial: Performance of job: 30 Practical: 3 hrs/week Notebook / Viva External Assessment On spot Job : 30 Viva Voce : 20 Credit: 2 Skill to be developed: **Intellectual Skill** Use of computer operation 1 **Motor Skill List of Practical** SI No. **Experiments** Simulate different electric circuit to prove theorems 2 Simulate different electric circuit to check resonance 3 Simulate different electronic circuit like amplifier, oscillator 4 Learning to write program in Matlab & analyze the output 5 Simulate the control system in Matlab Study the operation of LabVIEW software 6 VI, sub VI, loops, structure, chart, array, cluster, graphs etc **Books:** Title Author Publisher Virtual Instrumentation J Jerome PHI S Jain Wiley Matlab Bansal, Goel, Sharma Matlab & Its Application in Engineering Pearson LabVIEW Based Advanced P Sumathi Elsievier **Instrumentation System** LabVIEW graphical Programming Gray Jhonson TMH LabVIEW for Everyone Wells, Travis PHI Practical Matlab Application for M Kalechman Yesdee Engineers Advanced LabVIEW Programming Bittre, Mohiuddin, Nawrocki Techniques Automatic Control Systems with MATLAB Narendra Singh Beniwal & Ruby University Science Press (An inprint of Laxmi **Programming** Beniwal Publications Pvt. Ltd) Introduction to MATLAB & SIMULINK -O Bencher & M Weeks Firewell Media (An inprint of Laxmi A Project Approach Publications Pvt. Ltd) University Press Introduction to MATLAB Programming, Jaydeep Chakraborty Toolbox & Simulink

Syllabus for INDUSTRIAL PROJECT

Name of the Course: Diploma in Instrumentation and Control Engineering		
Name of the Subject : Industrial Project		
Course Code:	Semester: Sixth	

Duration: 6 months		Maximum Marks: 100	
Teaching Scheme:		Examination Scheme:	
Theory:		Continuous Internal Assessment: 50	
Tutorial:			
Practi	cal: 3 hrs/week	External Assessment : 50	
Credit: 2			
Aim:			
Sl No.			
1	This subject is intended to teach students to understand facts, concepts and techniques of		
	electrical equipments, its repairs, fault finding and testing, estimation of cost and		
	procurement of material, fabrication and manufacturing of		
2	This will help the students to acquire skills and attitudes		
	supervisor in industry and can start his own small-scale e	enterprise	
011 41			
Objective	e: The Student will able to		
Sl No.		-	
2	Work in Groups, Plan the work, and Coordinate the work Develop leadership qualities.	<u>. </u>	
3	Analyse the different types of Case studies.		
4	Develop Innovative ideas.		
-	Develop innovative ideas. Develop basic technical Skills by hands on experience.		
Pre-requ			
Sl No.	AUGUCC.		
1	Knowledge to execute student project.		
	F-Jess		
	Contents		
Project w	ork actually started on the last semester. It should be finish	ned in this semester. If students have finished one	
project or	n last semester. The will perform another project in this ser	mester	
Seminar o	on this project work is a part of this syllabus. Student will p	prepare the PPT for seminar & that will be	
	in front of external examiner. External examiner will eval		
	performance.	2 0	
Referenc	Deferences		
Kererenc	cs.		
IEEE Transactions/Journals			
Electrical India			
IEEMA Journal			
Elecrama			
Technora	ma		
Urja			
	Automation		
	Electronics for You		
Electronics Projects Computer World			
Computer World			
Chip Any Journal Related to Instrumentation / Electrical/Electronics/Computer/Information			
Website: http://www.google.com			
WEDSIE.	ntp.// www.googio.com		

Syllabus for PROFESSIONAL PRACTICE IV

Name of the Course : Diploma in Instrumentation and Control Engineering		
Name of the Subject : Professional Practice IV		
Subject Code: Semester: Sixth		

Durat	ion: 6 mon	ths	Maximum Marks: 50			
	ching Sche		Examination Scheme:			
Theory:			Continuous Internal Assessment: 50			
	utorial:					
Pr	actical: 2 l	nrs/week				
Credi	· 1					
Aim:	l. 1					
1	To acquire information from different sources					
2		nt given topic in a seminar				
3	-					
3		Prepare a report on industrial visit, expert lecture ntroduce FOSS				
Objec		idee 1 OSS				
Sl						
No.						
1	Prepare a report on industrial visit					
2						
4	Prepare notes for given topic.					
5	<u> </u>					
6		re a report on industrial visit, expert	lecture.			
	- I	· · · · · · · · · · · · · · · · · · ·				
Pre-r	equisite:					
1						
2						
3		ledge of basic computer operation f industrial visit				
4	Idea C	i ilidustriai visit	Contents			
Unit		Name of the activity	Contents	Hrs/Unit		
1		TO 11 X70 04				
1		Field VisitOne or two days Industrial visit in any plant				
		One or two days Industria	u visit iii any piant			
2		Lecture by Professional / Indu	strial experts / Student Seminar based on			
		following areas	-			
		(any four)				
		TOM				
		• TQM • Application of Pobotics is	n various fields			
		 Application of Robotics in various fields E Nose & E Tongue 				
		HART protocol				
		PLC DCS				
		• SCADA				
		MEMS and Application				
		Chemical and biosensors				
		Boiler Instrumentation and control				
		Intelligent control				
		Any other suitable topic				

3	Group Discussion The student should discuss in a group of six to eight students. Two topics for group discussions may be selected by the faculty members. Some of the suggested topics are- Civil servants or local politicians – who holds higher stature in India Liberalization and economic development Disaster management Shortage of skilled manpower in India Is foreign Direct Investment (FDI) in retail sector good for India? Adult education Trends in energy conservation Gambling/Betting should be legalized Any other suitable topic	
4	CAD for Electrical/ Electronics/ Instrumentation Drawing of electrical wiring, junction box, panel, equipments/ Instruments etc	
5	Free & Open Source Software • Revision of Libra Office, Writer, Calc, Impress, Latex	

Syllabus for GENERAL VIVA VOCE

	•	entation and Control Engineering	
	f the subject : General Viva Voce		
Subject Code:		Semester: Sixth	
Duration: 6 months		Maximum Marks: 100	
Credit:	3		
Aim:			
1	It is require d to revisit the contents of the departmental subjects learnt by the students up to sixth semester.		
2	As a diploma holder of Instrumentation and Control Engineering, students should be able to co relate the various ideas and concepts learnt from various subjects throughout the course duration		
3	Student should equip themselves to face various types of technical questions during various competitive examinations/ Interview Board.		
	_ L	Contents	
The syl	labi of all theoretical and sessional	l subjects taught in the three years of diploma education	
	ation Scheme:		
and one	e Internal Examiner. The External inent organization and he / she shoul	te place at the end of Sixth Semester. It is to be taken by one External Examiner is to be from industry / engineering college / university / d give credit out of 50 marks. The Internal Examiner should normally ne should give credit of 50 marks. In the absence of the Head of the	

Department, the senior most Lecturer will act as the Internal Examiner